We make car revolution happen

CANSim4

CANSim4 is a successor of CANSim3, a widely used rest-bus CAN simulator, which simulates the features of the entire car for the tested unit. The device is capable of simulating several different units at the same time.

It is mainly used for testing MIB and ICAS units. It can also be used for testing other units, in various demonstrators and in all use-cases, which require CAN simulations.

The main advantages of the CANSim4 are its small size, simple operation, comprehensive functionality and affordable price.

CANSim4 controls basic simulation signals using hand-held components, eliminating the need to use computer technology to control these signals.

Simulation signals (potentiometers):

- > Speed (0 240 km/h)
- > RPM (0 8000 r/min)
- > Backlight (0 100 %)
- Steering wheel angle (± 800°)
- > CNG, Water temperature, Clutch
- > Outside temperature, Accelerator

Simulation signals (switches):

- › KL.S / KL.15
- > Sleep
- Backlight (Day and Night mode)
- > PDC & Reverse

Key features

- ✓ 4× CAN interfaces (2 are CAN-FD compatible)
- 2× LIN interfaces
- 2× HS switches (e.g. KL.15 and KL.S simulation) and 1× LS switch
- ✓ BAP simulation
- ✓ RTC
- User programmable potentiometers and switches
- ✓ User defined rest-bus simulation
- LED indication of CAN and LIN communication
- ✓ Network management NM high
- Mini USB interface for firmware update and remote control
- Possibility of customized firmware modification
- Remote control over API
- CANSim Studio (own application for configuration of .dbc matrix)



Operating modes

- > Ten operating modes covering most applications
- > Modes for MQB, MQB37W and MEB platforms
- > Special modes for Infotainment test benches
- Special mode for MEB test bench (IgnSwExtV1 module is required)
- Mode which generates PWM-Signal "No Crash" (covering frequency of 10 Hz and 100 Hz)

CANSim Studio

CANSim Studio is a desktop application which supports CANSim4 device. It allows to update firmware automatically from the actualization server. In addition, the creation of user-defined simulations from .dbc matrix are possible. Signals can be set to static values or to dynamic and assigned to CANSim4 control elements.

E E	nodes nodes	Y	
- Message 1	Property	Value	
 M.T. Nachrick, Ungelkig M.S. ShirkZykisch, DirChange Message, 2 Message, 3 M.S. Sykkisch, Ungelkig M.S. Sz, Nicht/Sykkisch, DirChange Message, 4 Netricky, Ungelkig Message, 4 Netricky, Ungelkig M.S. Sz, Nicht/Sykkisch, Ungelkig M.S. Sz, Nicht/Sykkisch, Ungelkig M.S. Sz, Nicht/Sykkisch, Ungelkig M.S. Sz, Nicht/Sykkisch, Ungelkig 	E General		•
	Name	M3_S1_Zyklisch	-
	Modification type	Dynamic	
	Dynamic control	Potentiometer 2	_
	Pot, minimum raw value	0x0	
	Pot, minimum value	0.000000	
	Pot. maximum raw value 0x0 Pot. maximum value 0.000000		
	Value properties		
	Value type	Unsigned	
	Byte order	Intel	
	Start bit	0	
	Length	7	
	Unit		
	Factor	1.000000	
	Offset	0.000000	*
mal: M3_S1_Zyklisch	Modification type Constant - static value Dynamic - Value is set by contro		

Technical parameters

Supported platforms	MQB, MQB37W, MEB	
Weight	220 g	
Dimensions (w x h x d)	72 x 35 x 148 mm (including connectors and control elements)	
Power voltage	8.0 V to 18 V	
Operating temperature	-20 °C to 70 °C while preventing condensation	
Max. output load of KL.15 and KL.S	700 mA	
Built-in CAN terminators	120 $\Omega,$ switched by DIP switches on the rear panel	
CAN physical layer	In accordance with ISO 11898	

The device complies with the VW80000 (2009-10-01) requirement for functional state A (all parameters OK) in operating mode II.c (maximum permissible load).



For ordering, further details and available accessories please contact us: info@digiteqautomotive.com

